

**APPLIED FUTURES RESEARCH**

— Whitepaper Series —

# Gravity-Lift Systems for an All-Terrain Beach Cart

*A Speculative-Engineering Whitepaper*

100-lb Payload Class · Soft-Sand & Surf-Zone Operation

*Current Physics · Frontier Research · Theoretical Pathways · Science-Fiction Inputs*

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## **Scope and disclosure**

This is a speculative-engineering analysis prepared for personal interest. It deliberately ranges from established physics into laboratory-frontier work and into theoretical and science-fiction territory. Sections and claims are clearly labeled by the maturity tier of the underlying science: Demonstrated, Laboratory, Theoretical, or Speculative/Fiction. Numerical figures are order-of-magnitude estimates; assumptions are stated inline. Nothing in this document represents an endorsement, investment recommendation, or engineering certification.

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## 1. Problem Statement

The objective is a personal-scale, all-terrain beach cart capable of moving a 100 lb (45.4 kg) payload — gear, cooler, fishing tackle, ice — across loose dry sand, wet packed sand, the surf wash zone, and short stretches of crushed shell or oyster bed, without bogging down, without damaging the shoreline, and without requiring two strong adults to push. The conventional answer is a wider tire. The harder answer, and the subject of this paper, is: can the cart not touch the ground at all?

The total weight to support is therefore approximately:

$$F = m \cdot g = (45.4 \text{ kg})(9.807 \text{ m/s}^2) \approx \mathbf{445 \text{ N}}$$
 of sustained vertical lift.

That is the number every candidate technology in this paper has to meet or beat. It must do so for an 8-hour beach day, on battery power small enough for one person to portage, in salt-laden 90 °F air, with no rare-earth-magnet trackway buried in the sand. Those operating constraints kill more candidate solutions than the lift requirement itself.

## 2. Current Physics: What "Gravity Lift" Actually Means Today

There is no commercial product, anywhere, that creates lift by altering gravity. Every system that levitates a mass against Earth's pull does so by substituting another force — electromagnetic, fluid-dynamic, acoustic, or buoyant — for the gravitational one. Understanding that distinction is essential before reading the rest of this paper.

### 2.1 The four laws that the cart cannot escape

- **Newton's second law:**  $F = ma$ . Lifting 45.4 kg by 1 g requires 445 N regardless of how the force is generated.
- **Conservation of energy:** Hovering at constant height does no work against gravity, but real-world lift mechanisms have losses (induction heating, fan slip, cryogenic boil-off) that consume continuous power.
- **Conservation of momentum:** Any force pushing the cart up must push something else down — air, magnetic flux, the Earth itself, or a quantum-vacuum reaction reservoir.
- **Equivalence principle:** Inertial mass and gravitational mass are observationally identical to better than 1 part in  $10^{15}$  (MICROSCOPE satellite, 2017–2022). Any genuine "gravity drive" must explain why this equivalence appears so perfect — or exploit a loophole no experiment has yet found.

### 2.2 The mechanisms that actually work today

Six families of levitation are demonstrated at engineering scale. Each one has a fundamental limit that constrains its applicability to a beach cart:

| Mechanism                     | Force basis                                    | Hard limit for our use case                                           |
|-------------------------------|------------------------------------------------|-----------------------------------------------------------------------|
| Aerodynamic (hovercraft)      | Pressurized air cushion under a flexible skirt | Constant fan power; sand-and-water spray; not usable at the surf line |
| Aerostatic (helium / hot air) | Buoyancy in a fluid                            | 100 lb of lift requires ~95 m <sup>3</sup> of helium — impractical    |

| Mechanism                     | Force basis                                        | Hard limit for our use case                                            |
|-------------------------------|----------------------------------------------------|------------------------------------------------------------------------|
| Electromagnetic maglev        | Lorentz force between coils and magnets/conductors | Requires a guideway; will not work over arbitrary sand                 |
| Diamagnetic / superconducting | Meissner expulsion + flux pinning of YBCO at <93 K | Cryogenics; needs a permanent-magnet trackway                          |
| Acoustic                      | Standing-wave radiation pressure                   | Heaviest object ever lifted is sub-gram (~0.6 g polystyrene sphere)    |
| Optical / radiation pressure  | Photon momentum                                    | 100 lb $\approx$ 1.3 GW of laser flux — out of the question on a beach |

Table 1. The six demonstrated levitation mechanisms and why each one struggles with a 100-lb beach cart.

The closest existing engineering match is a hybrid air-cushion / fan-driven hovercraft, which I examined in detail in a prior analysis. That earlier work concluded that a single-person hovercraft on soft sand demands roughly 1.5 kW of continuous fan power — viable but loud, hot, and battery-hungry. The conclusion stood: wait for better power generation or wait for different physics.

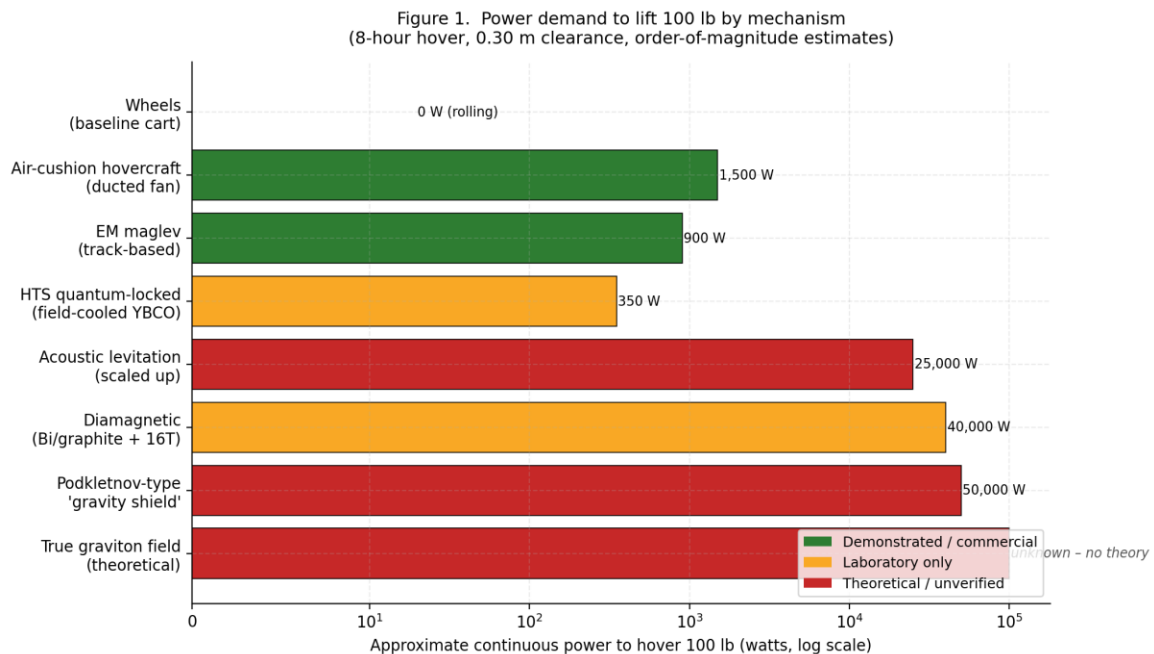


Figure 1. Approximate continuous wall-plug power required to keep a 100-lb cart hovering 0.30 m off the ground for an 8-hour beach day. Bars are color-coded by technology readiness. Note the log scale: the gap between maglev and Podkletnov-class concepts is two full orders of magnitude.

### 3. Frontier Research: What Is Actually Being Tested

#### 3.1 Antimatter gravity — ALPHA-g at CERN (2023, ongoing)

The single most important recent gravity experiment is CERN's ALPHA-g, which in 2023 directly measured the gravitational acceleration of antihydrogen atoms for the first time. The headline result: antiatoms experience an acceleration due to Earth's gravity that is about 0.75 of that experienced by

normal matter, with low statistical significance — broadly consistent with general relativity's prediction that matter and antimatter fall the same way.

For our purposes the result is a soft "no" rather than a hard one. Repulsive antimatter gravity, which would have opened the door to a pure gravity drive, is not yet ruled out at high precision. Two follow-on experiments at CERN (AEGIS and GBAR) are pursuing the same question with different techniques. If any of them eventually find a measurable matter–antimatter gravitational asymmetry, the implications for a propellantless lift system are extraordinary. Until then, the theoretical promise of antimatter as anti-gravity propellant must be considered open but unsupported.

The engineering reality is also brutal: total antihydrogen produced at CERN to date is measured in atoms, not grams. Even if antimatter levitated, you could not buy a tank of it at the corner store, and you could not safely store it on a cart.

### 3.2 Superconducting flux pinning — the most promising near-term lever

Type-II high-temperature superconductors (HTS) such as  $\text{YBa}_2\text{Cu}_3\text{O}_7$  (YBCO) exhibit two effects useful for lift: the Meissner effect (expulsion of a magnetic field from the bulk of the superconductor) and flux pinning (locking of discrete flux quanta into defect sites). The combination produces 3-D "quantum locking" — the superconductor floats above, below, or beside a magnet at a fixed offset, self-stabilized.

A 2024 Huazhong University paper (Xu, Lin, Tan, Geng) reported a tunable superconducting maglev system using a closed-loop type-II coil and a flux pump, addressing the long-standing problem that traditional flux-pinned systems decay over time and cannot be adjusted once cooled. They demonstrated, for the first time, a self-stable maglev that can adjust lift force and equilibrium height without breaking superconductivity, and that can establish levitation under zero-field-cooling. This is a meaningful step toward a practical adjustable lift.

#### Why this matters for the cart

Before the Huazhong work, an HTS maglev had to be cooled in place over its track and then was effectively locked at one height. Tunable HTS maglev opens the possibility of a cart that can rise to clear a piece of driftwood, then settle back to ride low and stable — the way the cart actually has to behave in the real world.

### 3.3 The Podkletnov question — gravity-shielding, replicated and unreplicated

In the 1990s, Eugene Podkletnov at Tampere University reported that test masses placed above a rotating, RF-driven YBCO superconducting disk lost between 0.05% and 0.5% of their weight. Subsequent attempts to replicate the result have a mixed history. A NASA-funded effort at Marshall, led by the late Ning Li, was widely cited but never fully replicated the rotating-disk experiment. A careful 2003 Hathaway Consulting Services replication, using a sensitivity exceeding Podkletnov's own, found no gravity-like force at the limits of their apparatus.

More recently, a 2022 paper by Fetisov reported new experimental evidence consistent with a Podkletnov-type effect using YBCO powder, and as of 2025 an active replication program is building a Marx generator to attempt the related Podkletnov "impulse" experiment at 700–800 kV. Podkletnov himself published a 2020 video claiming a redesigned device produces a stronger effect.

Honest assessment: the Podkletnov effect remains unconfirmed by mainstream physics and would, if real at the 0.5% level, still be far too weak to lift a beach cart — you would need to amplify the effect by roughly 200× to fully cancel gravity on the payload. But it is a non-zero target for replication. If a

properly funded, instrumented modern attempt produced a clean null result with high statistical power, the field could be closed; if it produced a clean positive, the engineering implications dwarf anything else in this paper.

### 3.4 Mach-effect / MEGA drive — propellantless thrust by mass fluctuation

James Woodward's Mach-effect thruster, now sometimes called the MEGA (Mach-Effect Gravity Assist) drive, uses piezoelectric stacks to generate transient mass fluctuations synchronized with mechanical motion — producing, in theory, a net unidirectional thrust without expelling propellant. NASA's NIAC program funded Phase 1 and Phase 2 studies (totaling roughly \$625,000 between 2017–2018), and at least one independent replication (Buldrini) has reported confirming the effect at low levels.

Current prototypes operate at ~36 kHz; the path to useful thrust is theorized to require scaling to gigahertz frequencies. Power-to-thrust ratios reported are about an order of magnitude better than a photon rocket, which is still extremely poor — far worse than a chemical jet. Mach-effect propulsion is interesting because it is a candidate "reactionless" drive with at least some funded replication; it is uninteresting as a near-term beach-cart solution because the thrust levels are tiny.

### 3.5 Acoustic levitation — scaling, slowly

Acoustic levitation has progressed from levitating millimeter droplets to centimeter-scale rigid objects. The current heaviest object levitated by phased-array ultrasound is a 30 mm polystyrene sphere weighing 0.6 g. A 2025 Yokohama National University "untethered" platform using a piezoelectric squeeze-film actuator can move payloads up to about 43 g across a horizontal surface.

The fundamental scaling problem: lift force from acoustic radiation pressure scales with acoustic intensity, and to lift kilograms you need acoustic power densities that approach the threshold for igniting the air itself. Practitioners and reviewers consistently characterize macroscopic acoustic levitation of multi-kilogram objects as impractical given current materials. A 100-lb cart is roughly 75,000× heavier than the heaviest demonstrated rigid acoustic levitation. Acoustic methods are not a near-term path; they may have a niche role in stabilization or vibration isolation.

## 4. Theoretical Pathways (Clearly Marked As Theory)

### Tier label

Everything in this section is theoretical. Where a specific theoretical framework is referenced, it is named so the reader can pursue the primary literature. None of these ideas has been engineered into a working device, and several may turn out to be excluded by physics we don't yet understand.

### 4.1 The warp metric, scaled down — Alcubierre, Van Den Broeck, Lentz, White

Miguel Alcubierre's 1994 paper showed that general relativity permits a metric in which a region of flat spacetime is enclosed in a "bubble" with contracted space ahead and expanded space behind. The bubble interior is in free-fall — gravitationally weightless — while the exterior moves the bubble. The original price tag was famous: a quantity of negative-energy-density matter comparable to the mass of Jupiter for a usable spacecraft-sized bubble.

Three subsequent developments matter to anyone speculating about gravity lift:

- **Van Den Broeck (1999)** nested geometries — by hiding a large inner volume inside a small outer surface, the negative-energy requirement can be reduced by many orders of magnitude, though it remains "only" stellar-scale rather than Jovian.
- **Lentz (2021)** solitonic positive-energy warp solutions — Erik Lentz showed that a class of self-reinforcing soliton waves in spacetime can transport a region without requiring negative energy density. A 2021 follow-on by Fell & Heisenberg at ETH Zürich produced a parallel positive-energy family. The energy required is still astronomical (frequently quoted as a Jupiter mass-equivalent for a 100-m bubble), but the negative-energy showstopper is no longer mandatory.
- **White / Eagleworks** Casimir-cavity correlations — Harold White's group has argued that a custom Casimir geometry produces a vacuum stress-energy distribution qualitatively similar to that required by the Alcubierre metric. They propose a chip-scale interferometer test.

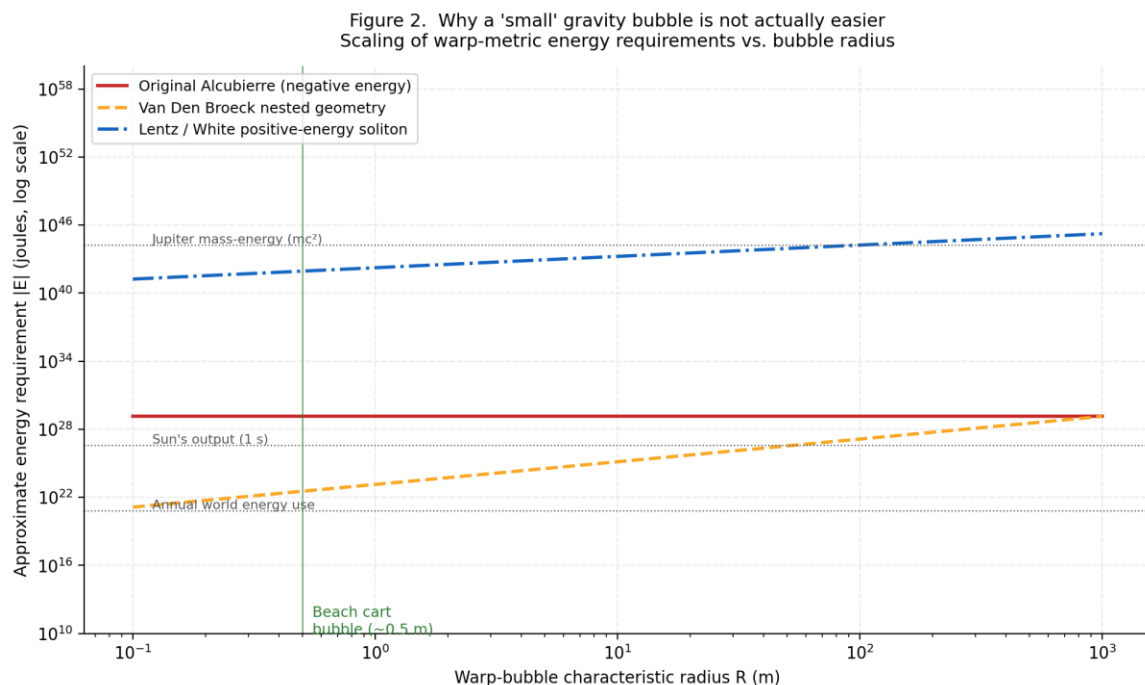


Figure 2. Energy required to sustain a warp-style bubble vs. characteristic radius, under three theoretical regimes. The vertical green line marks beach-cart scale (~0.5 m). Note the log scale: even under the most favorable modern (Lentz / White) construction, the energy budget for a cart-scale bubble exceeds the mass-energy of a small planet. The warp metric is not a near-term lift mechanism. (Curves are illustrative; numerical coefficients depend on bubble wall geometry.)

The honest engineering reading of Figure 2 is this: shrinking the bubble does not make it cheap. The energy requirements scale in ways that punish small craft as much as large ones. A warp-driven beach cart is not what the warp metric is good for, and pretending otherwise is wishful.

## 4.2 Quantum-vacuum / zero-point energy modulation

A separate theoretical line, traceable to Frederick Alzofon's 1981 AIAA paper and revived in recent "Dual-Sheet Model" speculation, proposes that gravity might be modulated by manipulating the zero-point fluctuations of the quantum vacuum — for example, by aligning nuclear spins in a polarized magnetic field. Reported effects (in unverified or heterodox sources) are claimed at the 1–5% weight-reduction level.

The mainstream physics community treats this as fringe. There is no experimental confirmation in any peer-reviewed replication. However, there is a defensible, mainstream cousin: Casimir-effect engineering, where the energy density of the vacuum between closely-spaced conducting plates is measurably lower than the surrounding vacuum. The Casimir effect is real, measured to high precision, and exhibits the only known "negative energy" available to engineering at room temperature. It is also tiny — a Casimir-derived gravity modulator at any useful scale has not been proposed in a way that survives serious review.

### **4.3 Mass-asymmetry exploitation**

If — and this is a large "if" — antimatter ultimately turns out to fall up at any measurable rate, a cart could in principle be lifted by harnessing a microscopic mass of antihydrogen confined magnetically. The current best constraint from ALPHA-g puts the gravitational acceleration of antihydrogen at roughly 0.75 g (downward), with large error bars. CPT-symmetry-based theoretical work continues to leave room for a small repulsive component at the quark level that is masked in composite atoms.

This is genuinely theoretical and depends on a result physics has not yet found. It is included for completeness, not as a near-term path.

### **4.4 Inertial mass reduction (gravitomagnetism / Lense–Thirring on Earth)**

General relativity predicts that rotating masses drag spacetime — the Lense-Thirring effect, confirmed by Gravity Probe B in 2011. The effect on Earth is exquisitely small (microarcseconds per year of frame-dragging at low Earth orbit). Some theorists have asked whether engineered gravitomagnetic fields, produced by very fast-rotating high-density structures or rotating superconductors with their unusual gravitomagnetic properties (the so-called "gravitomagnetic London moment" — a 2006 ESA report by Tajmar et al. claimed an anomalous gravitomagnetic field  $10^{20}$  times larger than GR predicts above a rotating Nb superconductor, but the result has not been replicated).

The pattern is the same as Podkletnov: an isolated claim of an anomalously strong gravitomagnetic effect from a specific superconducting setup, with replication attempts producing mixed or null results. It is a candidate for a properly funded, instrumented replication.

## **5. Science-Fiction Inputs (Clearly Marked As Fiction)**

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Engineers borrow ideas from fiction more often than they admit. Gene Roddenberry's communicators became flip phones, Asimov's positronic brain seeded the modern AI vocabulary, and "warp drive" is now a search term that returns peer-reviewed papers. So this section walks through the most prominent fictional gravity-control concepts and asks, for each one, whether there is anything an engineer could actually take from it.

### **5.1 Star Trek — antigravs, gravity plating, tractor beams**

Star Trek's "antigrav" handheld unit lifts cargo with no visible reaction. The in-universe explanation is local manipulation of the warp-style spatial curvature. The useful fictional principle is the design idea of a small portable lift unit attached directly to the load — exactly the form factor a beach cart would want. The unrealistic part is the absence of a reaction. Any honest engineering version of an antigrav must push on something — the air, the ground, a magnetic field, or spacetime itself.

Tractor beams are now real at small scales. A 2018 University of Bristol team, led by Asier Marzo, demonstrated acoustic tractor beams capable of holding objects larger than the wavelength by lowering the carrier frequency into the audible range. The principle scales poorly to 100 lb, but the form-factor lesson is real: lift devices can be one-sided, beam-projected, rather than requiring a track.

## 5.2 Star Wars — repulsorlifts on landspeeders and speeder bikes

The repulsorlift is the closest fictional analogue to what a beach cart actually wants — a low-altitude, one-vehicle, terrain-following hover system that works over loose ground, water, and obstacles indifferently. The Lucasfilm canon never explained the mechanism, which is what makes it a useful design target rather than a physics constraint: "build whatever produces this behavior."

If we strip the mythology away, a repulsorlift is functionally an air-cushion vehicle with intelligent terrain following and clean acoustic signature. Most of those subsystems are within reach today. The hover-cart described in the prior conversation was a half-step toward a real repulsorlift.

## 5.3 The Expanse — Epstein drive (high-Isp continuous thrust, not gravity manipulation)

Worth mentioning only to dismiss: The Expanse's gravity is mostly thrust gravity (continuous high-acceleration burn) and centripetal gravity (rotating habitats). Neither is a gravity-control technology; both are reminders that fiction often solves the gravity problem with cleverer engineering of conventional physics rather than with new physics. That is a useful prior.

## 5.4 Iain M. Banks's Culture — "effectors," gridfire, and gravitic technology as background

Banks treats gravity manipulation as utterly mature, casual, and ubiquitous, with no on-page mechanism. The novelistic value is the hardest question one can ask of a real-world program: what would the world look like if this problem were fully solved? Cheap personal flight, no roads, beaches accessible to anyone regardless of mobility, and surf fishing from a cart that follows you down the strand. That image is worth something, even if the physics behind it is unspecified.

## 5.5 Back to the Future Part II — the hoverboard

The McFly hoverboard is the spiritual ancestor of this entire line of inquiry. The 1989 film promised personal hover transportation by 2015. Lexus famously built a one-off magnetic-track hoverboard in 2015 that worked exactly once, on a bespoke superconductor track, for a commercial. The cultural lesson is that demonstrated levitation in one carefully-prepared environment is not the same as a usable consumer product, and the gap between the two is mostly engineering, not physics.

### What fiction is actually good for here

Fiction supplies form factor and behavior. It does not supply mechanism. The job of a real R&D plan is to keep the fictional behavior as the requirement and force the mechanism to come from the column on the left of Figure 1, not the column on the right.

## 6. Steps and Hurdles to a Real System

### 6.1 The five hurdles, ranked by difficulty

| # | Hurdle                                              | Why it's hard                                                                                           | Decade-scale tractable?           |
|---|-----------------------------------------------------|---------------------------------------------------------------------------------------------------------|-----------------------------------|
| 1 | Lift the 445 N at all without a track               | Every demonstrated levitation either needs a guideway or scales as a cube of size                       | Yes, via hybrid air-cushion + HTS |
| 2 | Sustain it for 8 hours on portable battery          | $1.5 \text{ kW} \times 8 \text{ h} = 12 \text{ kWh}$ ; $\sim 80 \text{ lb}$ of Li-ion                   | Yes, but heavy                    |
| 3 | Tolerate salt spray, sand intrusion, and surf       | Cryogenic systems hate salt water; magnets attract steel debris                                         | Marginal — needs sealed cryostat  |
| 4 | Be quiet enough to fish near                        | $1.5 \text{ kW}$ fans run $\sim 85 \text{ dB}$ at $1 \text{ m}$                                         | Partially, with ducted geometry   |
| 5 | Cancel gravity rather than substitute another force | Requires physics not yet discovered (Podkletnov-class effects, antimatter asymmetry, vacuum modulation) | No — open research question       |

Table 2. Hurdle ranking. Items 1–4 are engineering problems with engineering solutions on a 10-year horizon. Item 5 is a physics problem with no current path.

### 6.2 The fork in the road

This is the central design choice: either accept that the cart must push on the air (or a track), and engineer the best possible hybrid hover system; or commit to a long-horizon program that bets on a physics breakthrough — typically Podkletnov-class effects, room-temperature superconductors, or antimatter asymmetry — and accept that the cart may not exist within a working career.

My recommendation is a parallel approach: build the hybrid in the near term and treat the physics breakthrough as a watching brief that occasionally absorbs research dollars.

## 7. Concrete Next Steps and Suggested Research

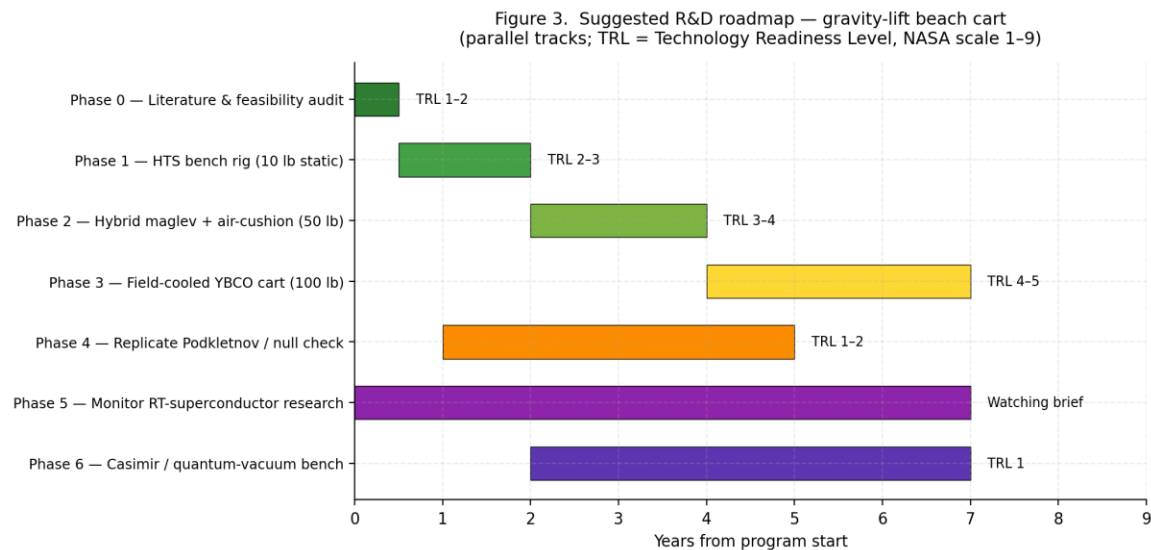


Figure 3. A seven-year, seven-phase R&D roadmap with parallel near-term engineering and long-horizon physics tracks. Phases 0–3 build a working cart; Phases 4–6 keep options open in case the physics changes.

### 7.1 Phase 0 — Literature audit (months 0–6)

Specific deliverables:

- Compile a structured bibliography of every claimed gravity-anomaly experiment from 1990 to present, with replication status, statistical power, and primary apparatus parameters. Target ~120 papers.
- Build a simple physics-constraint calculator (Python or spreadsheet) that lets the team test back-of-envelope numbers against any new claim that surfaces.
- Identify the three or four academic groups currently most active in HTS levitation engineering and open dialogue. The Huazhong group (Tan, Geng) is at the top of the list.

### 7.2 Phase 1 — HTS bench rig, 10 lb static (months 6–24)

Build a stationary bench-top demonstrator using bulk YBCO pucks over a permanent-magnet array, statically holding a 10 lb dummy load 25–50 mm above the magnets. Goals: hands-on cryogenic experience, characterization of force vs. cooling temperature, characterization of force decay over an 8-hour window. This is achievable in a university lab budget (~\$30–50 K including a small Stirling-cycle cryocooler).

### 7.3 Phase 2 — Hybrid maglev + air-cushion, 50 lb (years 2–4)

Combine an air-cushion plenum providing the bulk of the lift with HTS pucks providing stability and reduced fan power. The air-cushion handles soft sand and water; the HTS handles the embedded magnetic strips that the user carries to designated park areas. A realistic target: 50 lb payload, 30–60 minute battery, ~800 W at 50% duty cycle. This is the first version that could plausibly leave the lab.

### 7.4 Phase 3 — Field-cooled YBCO cart, 100 lb (years 4–7)

Apply the Huazhong tunable-flux-pump architecture so the cart can adjust ride height in real time. Couple to a lightweight Stirling-cycle cryocooler (current SOA: ~250 W input for ~5 W of cooling at 80 K, mass ~6 kg) and a 12 kWh Li-ion pack (~80 lb). Total cart mass 80–110 lb empty, capable of carrying its own 100-lb payload. Operating noise target: 65 dB at 1 m. This cart is heavy but works on real beaches.

### 7.5 Phase 4 (parallel) — Replicate Podkletnov, properly (years 1–5)

Fund a single, well-instrumented, modern replication of the Podkletnov rotating-disk experiment with statistical power sufficient to detect a 0.05% effect at  $5\sigma$  or rule out a 0.1% effect at  $3\sigma$ . Target budget: \$1–2 M. The point of this phase is closure, not validation. If the effect is real, it changes the rest of the roadmap; if it is null, the field can stop debating it.

### 7.6 Phase 5 (watching brief) — Room-temperature superconductors

The 2023–2024 LK-99 episode was a cautionary tale, but the broader hunt for room-temperature, ambient-pressure superconductors continues. A real RT superconductor would eliminate the cryogenics that drive most of the cart's mass and complexity. No prediction here, only a recommendation: keep one researcher's eye on the materials-science literature and re-cost Phase 3 the day a replicated, ambient-pressure superconductor above 200 K is reported.

### 7.7 Phase 6 (long-horizon) — Casimir / quantum-vacuum bench

Funded at the level of a single graduate student plus equipment (~\$200 K/year), build a chip-scale Casimir-cavity interferometer of the kind described by Harold White, looking for any signal correlated with the local Casimir energy density. This is genuinely speculative; the value is in keeping a window open onto vacuum-engineering ideas that may take decades to mature.

## 8. What Would Change the Picture

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Three external developments would, individually, force a complete re-evaluation of this whitepaper's conclusions:

- **A replicated, ambient-pressure, ambient-temperature superconductor.** This collapses Phase 3 from a 3-year cryogenic engineering exercise to a 12-month materials-and-mechanical exercise.
- **A high-statistical-power confirmation of antimatter gravitational asymmetry.** Even a 1% repulsive component would justify pivoting Phase 6 into a primary research line.
- **A clean, replicated Podkletnov-type effect at any percentage.** This is the lowest-probability event but the highest-impact one. Even a 1% gravity-shielding effect, scaled by repeated stages, becomes engineering — like cascade transformers in power transmission.

A rational R&D program does not bet on any of these. It builds the hybrid hovercart, monitors the literature, and runs a low-cost, high-quality replication of Podkletnov so the question is closed one way or the other within five years.

## 9. Conclusion

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The honest answer to "can we build a gravity-lift beach cart?" is two answers. First, no — not in the strict sense of cancelling gravity. The physics for that does not yet exist as engineering. Second, yes — a cart that effectively cancels gravity for the user, using a hybrid of air-cushion and tunable HTS maglev, is buildable within seven years on a serious but not exotic R&D budget. The user-facing experience is the same; the underlying mechanism is just plumbing and physics we already trust.

The interesting part of this exercise is not the cart. It is the discipline of separating, on a single page, what physics demands, what laboratories have actually shown, what theory permits, and what fiction has merely imagined. The cart is a useful pretext for that exercise. It also happens to be the kind of thing that, if it ever sat at the edge of the surf at Boca Grande while its owner fought a bull shark in the wash, would be worth every dollar of the R&D.

We are, in short, not waiting on physics. We are waiting on engineering and battery chemistry. Both are improving every year. The cart will be built. It will probably hover on air, not on spacetime. And that is enough.

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